

# A Survey-An Efficient Flooding Scheme for Mitigating Broadcast Storm Problem in Wireless Sensor Network

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**Abstract-** Flooding is a convention that conveys a message from one node to the next whole nodes inside the remote sensor system. The immaculate flooding makes all the nodes to rebroadcast the bundle in any event once. These outcomes in the broadcast storm issue. So the system assets turn out to be seriously squandered. So as to take care of the broadcast storm issue, this paper proposes a productive flooding plan which is a cross breed of the likelihood based technique and the neighbor data based strategy. To keep away from the crashes between close neighbors, this strategy receives the back-off delay plan.

**Keywords-** broadcast storm; flooding; wireless sensor network

## I. INTRODUCTION

Flooding is a network layer protocol that delivers a message from one node to all the other nodes inside the network. Flooding is a basic operation for time synchronization [6], data dissemination [1, 2], node localization [7], and routing tree formation [3] in wireless sensor networks.

The flooding is regularly utilized strategies for nodes to trade system data, convey directing solicitation messages to destination. The essential flooding is likewise called as blind flooding or pure flooding. Each node rebroadcast the first run through got parcel precisely once. The aggregate movement turns out to be too substantial since each node must rebroadcast the bundle at any rate once. This outcomes in congestion [4], collision [5], and excess transmissions. These are all things considered speaks to telecast storm issue in WSN. Due to the broadcast storm issue the execution of WSNs turns out to be low. Likewise wastage of assets like power and bandwidth, the crash and discord are vast costs to sensor systems since they are relies on upon battery power which can't be energized.

Such a large number of flooding plans have been intended to alleviate the broadcast storm issue in remote systems. They attempt to minimize the retransmission of duplicate packets in light of fundamental system data, for example, location, retransmission likelihood. The strategies that utilization the quantity of neighbor nodes, not the precise neighbor rundown, has been outlined. Additionally, the more particular data like neighbor node rundown is used to minimize the quantity of duplicate packet transmissions. Be that as it may, this study requires the substantial costs to keep the right and precise neighbor node list.

In this paper a system is proposed which make utilization of the neighbor hub condition in an alternate manner from the past systems. The neighbor hubs are isolated into 3 sorts: Parent, sibling, and child nodes. The node-type data is acquired amid a few seasons of beginning flooding from a sink node. In the event that the node has more siblings there is a higher likelihood that its child nodes gets a packet, even it is not ready to retransmit the packet instantly. In this way, more sibling a node have, its retransmission likelihood may be diminished. Meanwhile, if a node has numerous child nodes, it needs to rebroadcast the packet with a higher likelihood on the grounds that all the child notes are secured by the sibling nodes retransmission. So retransmission likelihood is corresponding to the quantity of child nodes and conversely relative to the quantity of sibling nodes.

## II. RELATED WORK

The flooding plans can be arranged into two sorts: heuristic-based and topology-based plans. The primary plan uses data on the duplicate packets got; the second one uses the topology data. The heuristic-based strategies can be further separated into probability-based and area-based. Meanwhile topology-based plans can be ordered into neighbor

data based, source-tree based, and cluster- based calculations [8, 11].

In the probabilistic plan, when a node gets a packet and it advances packet with likelihood P. The estimation of P is gotten by the data present at every node. In a distance based plan, a node works in view of a threshold D. On the off chance that the separation between the source and sink is more prominent than D, the node rebroadcasts the message. In a area- based plan rebroadcasts the message if the extra scope because of the new emission is bigger than a bound A. The neighbor information plan [12] check neighbor node data to choose which node ought to rebroadcast once more. This system obliges sensor nodes to trade neighborhood data utilizing intermittent hello packets. The neighbor list at the present node is added to each broadcast packet. At the point when the present node gets a packet from the neighbor, it contrasts and its neighbor or rundown with the rundown recorded in the packet. It rebroadcasts the packet if not every of its own neighbors are incorporated in the rundown recorded in the packets. The source-tree based plan builds a broadcast tree, and afterward every single broadcast packet move along branches of the tree.

At long last, the cluster based plan isolated the network into number of clusters. Every cluster has one cluster head. The cluster head is a delegate of the group whose rebroadcast can cover all hosts in that group. Just a cluster head can speak with different clusters and have obligations to disperse the broadcast message to different memberships.

The proposed method is a mixture of the probability based technique and the neighbor information based strategy. The proposed technique sets the retransmission probability of broadcast packets like the probability based system, yet the probability can be distinctive for every sensor node relying upon the neighbor node data. Nonetheless, the neighbor data is gathered once at the system starting time in light of the fact that sensor nodes are thought to be static normally.

### III. BROADCAST STORM PROBLEM

A straight-forward way to deal with perform broadcast is by flooding. A node, on accepting a broadcasting message interestingly, has the obligation to rebroadcast the message. This expenses n transmission in a system of n has. In a CSMA/CA system, disadvantages of flooding include:

- *Redundant rebroadcasts:* When a host chooses to rebroadcast a broadcast message to its

neighbors, every one of its neighbors as of now has the message.

- *Contention:* After a host broadcasts a message, if a large portion of its neighbors choose to rebroadcast the message, these transmissions might extremely contend with one another.
- *Collision:* Because of the deformity of back off system, without CD, impacts are more prone to happen and cause more harm. Collectively, we refer to the above phenomena as the broadcast storm problem

### IV. PROPOSED ALGORITHM

In the current dynamic probabilistic flooding, the retransmission likelihood is balanced by number of duplicate packets got inside of a time of time. The proposed plan makes utilization of the neighbor node data to register the retransmission likelihood. The proposed strategy characterizes neighbor hubs into three classes of hubs: parent, sibling, and child nodes.

The more sibling a node has, there is a less need of retransmission if the node has more siblings such that every one of its child may get a broadcast packet. The node may not retransmit the packet, on the off chance that its child nodes will probably get the packet from sibling of that node. In the meantime, if a node has numerous child nodes its retransmission probability ought to be high. Along these lines, the two terms the quantities of siblings and child are utilized as a part of this plan so as to accomplish more efficient and reliable flooding.

The proposed calculation is involved with three stages. In the first place, nodes get neighbor data through the trading of Hello messages. Second, the nodes get their level inside of the topology tree and register the relation with their neighbors. At last, the nodes resolve the retransmission probability on the premise of quantities of child and sibling nodes. After that, each node advances a packet as indicated by its retransmission probability.

#### *Step 1: Basic flooding*

Nodes need to gather the neighbor data at first. In this step, the basic flooding is utilized. Fig. 1 illustrates an example of collecting information on neighbors. The neighbor list table of a node comprises of neighbor data, for example, Neighbor ID, Level, Relation Type (P: Parent node, S: siblings, C: child nodes), and in addition its own level. The data of the parent can be acquired when a node, say node 1, gets a packet first from the parent, and the data on the siblings and child nodes is known when

they rebroadcast the packet which node 1 conveyed to them.

In the fig 1, node 1 becomes acquainted with that nodes S and 2, 4, 5 are its neighbors by trading the Hello messages. At that point, the sink hub S broadcasts a packet. The node S level and connection are set to 0 and P (Parent). At the point when the node 2 retransmits the packet, the level and relation of node 2 are set to 1 and S (Sibling). At long last, nodes 4 and 5 retransmit the packet which has gotten from node 1, so their levels and relations are set to 2 and C (Child). The node 1 counts the quantity of nodes having a place with every sort of relation after the broadcast is finished.

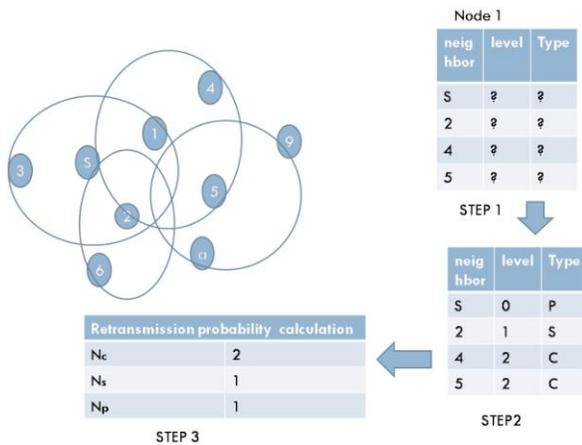


FIGURE 1: COLLECTING NEIGHBOR INFORMATION

In the meantime, the relation between nodes is not settled dependably. In wireless networks because of contention or collision, the way from the sink to a node is not generally the same. For each broadcast relation with a neighbor may be changed, e.g., from a sibling to a child or from parent to a sibling, etc.

Figure 2 portrays this issue. In the first figure. Node C is a sibling of node D. Nonetheless, in the second figure it can be a child of a child node of node D.

The packet transmission through wireless channels is influenced by such a large number of factors, including collisions and contention, which are more serious in a system with a high node density. So in the denser network the more relation changes may happen. One time broadcasting may not be sufficient to choose the kind of relation with all neighbor nodes when we consider the nodes redundancy as it is a standout amongst the most essential feature of WSN. Through beginning five times of the essential flooding this strategy figures the probability of every type of relation with itself.

Table 1 portrays an illustration of the probability computation by node X. Node X through trading Hello messages establishes that it has 6 neighbors and these neighbor node IDs are gathered. Node A is forever its parent for the five times of flooding, so Parent of node A is 1 and node B is a parent two times and a sibling three times among the five times of flooding, subsequently parent = 0.4 and sibling = 0.6. So finally, each of Pparent, Psibling, and Pchild is included up the segment premise, being meant by Np (the number of parents), Ns (the number of siblings), and Nc (the number of child). Subsequently, node X has 1.6 parents, 2.2 sibling, and 2.2 child nodes by and large. These Np, Ns, and Nc are utilized to figure the retransmission probability in the following step.

The five times of beginning flooding build vitality utilization when contrasted with the past plans which requires only one time flooding. At any rate, this may not be too substantial an overhead, in light of the fact that the WSN topology is static in typically by considering that the impact of exact probabilities on the execution goes on for quite a while. In a mobile adhoc networks, the late five times of flooding can be utilized all the time to register the retransmission probabilities set up of the five times of initial flooding.

### Step 2: Computing retransmission probability

The transmission probability  $P_t$  is calculated as in Equation(1).

$$P_t = \begin{cases} 0 & , N_c = 0 \\ \max \left[ \left( \frac{1}{N_s + 1} + P_i \times \frac{N_c}{N_n} \right), 1 \right] & , \text{others} \\ 1 & , N_c > 0, N_s = 0 \end{cases} \quad (1)$$

Here Nc, Ns, and Np mean the numbers of child nodes, sibling nodes, and parent respectively. Nn is the total number of neighbor nodes.

On the off chance that a node has no child, the retransmission is not required and, in the event that it has recently child nodes, it must retransmit a packet. In different cases, the retransmission is performed by probability  $P_t$ .

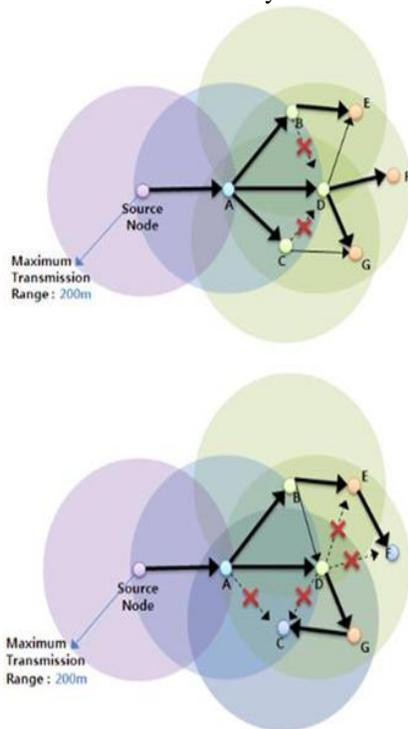
The first term,  $1/(Ns+1)$ , implies it needs the lower retransmission probability when with a has more sibling.

The second term,  $P_i N_c / N_n$ , is appended to the equation. If the node has more child nodes, the larger

Neighbor Information List of Node-X(Level/Relation)												
Number	ID	[1]	[2]	[3]	[4]	[5]	Pparent		Psibling,		Pchild	
1	A	1/P	1/P	...	...	...	1.0		0		0	
2	B	2/S	2/P	...	...	...	0.4		0.6		0	
3	C	2/S	3/S	...	...	...	0		1.0		0	
4	E	2/S	4/C	...	...	...	0.2		0.4		0.4	
5	F	3/C	3/S	...	...	...	0		0.2		0.8	
6	G	3/C	4/C	...	...	...	0		0		1.0	
Level of Node-X		2	3	...	...	...	NP	1.6	NS	2.2	NC	2.2

TABLE I: EXAMPLE OF COMPUTING THE NEIGHBOR NODE RELATION

Probability it adds. Here,  $P_i$  is an initial probability based on the node density.



Element	Description
●	Sensor node
→	The path of flooding message that comes first (create topology)
→	The path of flooding messages other than the first arrived message
...X→	Unsuccessful flooding message (bidirectional or unidirectional disconnection)

FIG 2: EXAMPLE OF TOPOLOGY CHANGE

Nodes/Range	Initial probability
0-3	1.0
4-5	0.9
6-7	0.8
8-13	0.7
14-30	0.6
31	0.5

TABLE II: INITIAL PROBABILITY ( $P_i$ )

### Step 3: Packet Retransmission

Each Every node rebroadcasts the packet as per its retransmission probability  $P_t$ . So there may be risk of an excess of packets impacts. This is on account of every single sibling node in like manner endeavor the retransmission the moment they get a packet. This issue can be settled by permitting every node hold up an irregular back-off delay before retransmission.

The probability of collision is generally corresponding to the quantity of neighbors. In this manner in this plan, the back-off time for every node is situated to  $d * N_s$  (the number of siblings), where  $d$  is a time unit that can be acclimated to the genuine network environment.

## CONCLUSION

This strategy is one of the dynamic probabilistic plans utilizing the quantities of child and sibling nodes. The node has higher retransmission probability on the off chance that it has the more child nodes and the less sibling nodes. This technique needs starting overhead because of the initial five occasions of flooding; however it will outflank the various routines in the part of the quantity of retransmissions as we talked about in the working illustration.

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